

## Compressor Drive Quick Guide

133R6015 V2019-01  


### 1.Basic information

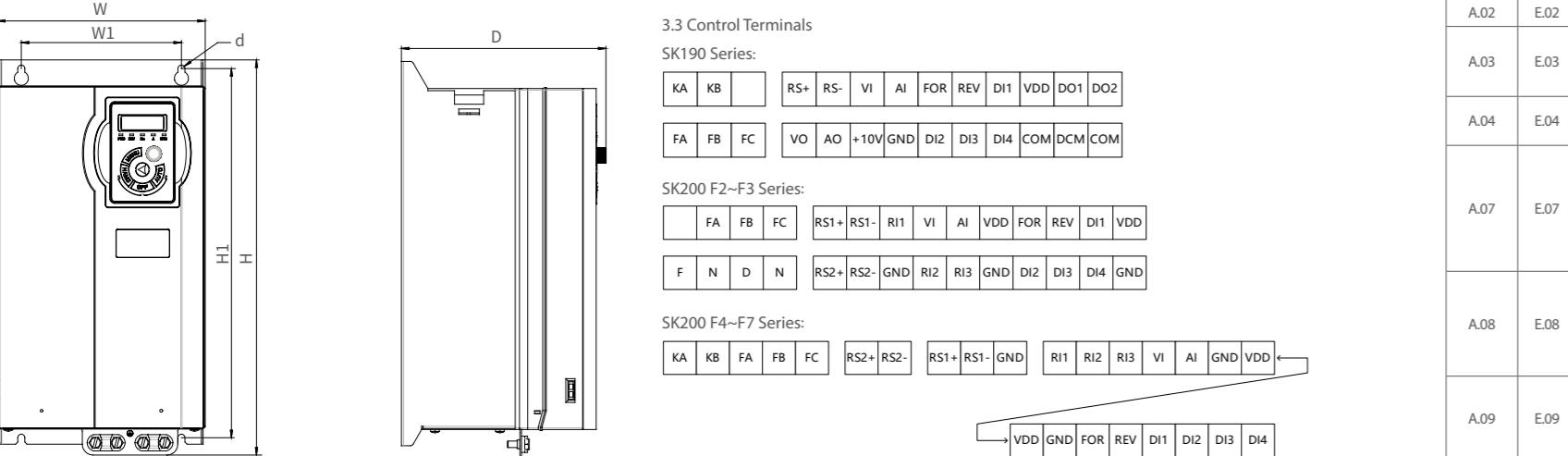
This document will guide the customer to complete the basic installation, wiring and functional debugging. For detailed instructions, please contact your supplier. All products are strictly tested and packaged before leaving the factory. If the drive is found damaged, wrong model, lack of additional accessories or other abnormal conditions, please contact the supplier.

#### A Danger

Please read and understand this manual before installing or operating the drive. Please install, debug, overhaul and maintain the drive by professionals.

- Be sure to cut off the power supply before wiring.
- Before touching any potentially live parts of the drive, please wait at least 4 minutes for the drives of less than 22kW (including 22kW), and wait at least 15 minutes for the drives of more than 30kW (including 30kW), when it is cut off. Otherwise, it may expose you to a risk of electrical shock.
- Do not plug the connectors of the drive during the power up to avoid any surge into the main control board due to plugging, which might cause the damage of the drive.
- R.S.T terminals are power input terminals, never mixed with U.V.W terminals. Be sure that the wiring of the main circuit is correct. Otherwise it will cause damages of the drive when the power is applied to it.
- The ground terminal must be grounded separately and never connected to N-line.
- Failure to follow instructions could result in serious casualties.

### 2. Installation Dimensions



### Voltage & Power Dimensions (mm)

Model	Frame	Voltage & Power		Dimensions (mm)					
		3x200-240V	3x380-440V	W	H	D	W1	H1	d
SK190	F1	-	4.0-5.5kW	145	250	167	124	230	4.5
	F2	-	7.5 kW	155	263	177	133	243	4.5
	F3	7.5kW	11-15kW	192	365	189	150	340	6.5
	F4	11kW	18.5-22kW	216	420	194	150	340	6.5
	F5-1	15-18.5kW	30-37kW	292	517	229	240	492	9
	F5-2	22-30kW	45-55kW	292	562	249	240	537	9
	F6	37kW	75kW	292	665	277	240	640	9
	F7	-	90-132kW	350	799	375	220	765	10.5
	F8	-	160-220kW	486	900	390	345	863	10.5
	F9	-	250-415kW	600	1568	509	524	1578	15
SK200	F2	-	7.5kW	158	340	178	133	330	4.5
	F3	-	11-15kW	194	440	190	150	426	6.5
	F4	-	18.5-22kW	234	509	210	150	491	7
	F5	-	30-37kW	292	599	230	240	574	9
	F6	-	45-55kW	292	650	249	240	625	9
SK300	F7	-	75-90kW	292	742	278	240	717	9
	F2	-	7.5kW	176	310	179	126	300	5.5
	F3	-	11-15kW	210	360	188	166	350	5.5
	F4	-	18.5-22kW	265	427	219	221	405	9
	F5	-	30-37kW	320	457	219	240	436	9

### 3. Specification and Wiring

#### 3.1 Rating of Motor

Drive Power(kW)	Host Power(kW)	Cooling Power(kW)
7.5	7.5	0.5
11	11	0.5
15	15	0.8
18.5	18.5	1.5
22	22	1.5
30	30	1.5
37	37	1.5
45	45	2.2
55	55	2.2
75	75	5.5
90	90	5.5

Note: Other models only support host motor.

#### 3.2 Main Circuit

Symbol	Function	Description
R、S、T	Power input	3x380~440V -20%~+10%;
U、V、W	Host output	IM/PM Motor
U1、V1、W1	Cooling output (Fan 1)	IM/PM Motor; Host power≤15kw, controlled by contactor; Host power≥18.5kw, controlled by drive;
U2、V2、W2 (optional)	Motor Fan (Fan 2)	Fan for motor, controlled by contactor.

Note: SK190 Series(380V Class) support up to 528V input voltage.

#### 3.3 Control Terminals

##### SK190 Series:

KA	KB		RS+	RS-	VI	AI	FOR	REV	D1	VDD	D01	D02
FA	FB	FC	VO	AO	+10V	GND	D12	D13	D14	COM	DCM	COM

##### SK200 F2~F3 Series:

FA	FB	FC	RS1+	RS1-	RI1	VI	AI	VDD	FOR	REV	D1	VDD	
F	N	D	N	RS2+	RS2-	GND	R12	R13	GND	D12	D13	D14	GND

##### SK200 F4~F7 Series:

KA	KB	FA	FB	FC	RS2+	RS2-	RS1+	RS1-	GND	R11	R12	R13	VI	AI	GND	VDD
VDD GND FOR D11 D12 D13 GND VDD GND VDD VI AI R11 GND R12																

##### SK300 Series:

RS+	RS-	GND	VDD	GND	FOR	D11	D12	D13	GND	VDD	GND	VDD	VI	AI	R11	GND	R12
FA	FB	FC	F	N	D	N											

#### Terminals' specification:

Symbol	Function	Description
VDD	24V Power Supply	SK300: 600mA; SK200 F2~F3: 270mA SK200 F4~F7: 500mA
FOR, REV, D11, D12, D13, D14	Digital input	1. Logic: >DC 19V Logic:0; <DC 14V Logic:1; 2. Voltage: DC 0-24V; 3. Input resistance: 5kΩ; 4. Input voltage Rang: Max ±30V; 5. D12, D13, D14 support PTC sensor;
VI, AI	Analog input	Both VI and AI can be configured to 0-20mA or 0-10V by parameters: VI default: voltage input; AI default: current input; 1. Input Impedance: about 10kΩ; 2. Input Impedance: ≤500Ω;
COM	Control ground	Digital ground for SK190
GND	Control ground	Analog and communication ground for SK190; Digital, analog and communication ground for SK200/SK300;

Symbol	Function	Description
DO1、 DO2	Digital output	1. Open collector output; 2. Output current range: 0-50mA; 3. Max voltage 30V;
FA-FB-FC KA-KB	Relay output	1. Resistive Load: 250VAC 3A/30VDC 3A; 2. Inductive Load: 250VAC 0.2A/24VDC 0.1A ( $\cos\phi=0.4$ );
F-N 、 D-N	Relay output (220V)	With 220V power supply, it is necessary to pay attention to safety when using, and the D-N is fixed as the function of the loading valve.
RS+、 RS-、 RS2+、 RS2-	Communication	Max baud rate: 115200bit/s;

#### 3.4 LED Specifications of SK300

Indicator Light	Status	Description





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Par. No.	Name	Range	Unit	Default
C01.70	PM start mode	0: with IPD; 1: without IPD;	-	0
C01.71	Start Delay	0~10.0	s	0.0
C01.76	Jump Frequency	0~20.0	Hz	0
C01.80	Function at Stop	0: Coast 1: DC hold	-	0
C01.82	Min Speed for Function at Stop	0.0~400.0	Hz	*
C01.91	Motor overload protection time	1~60	min	2
C01.92	Motor overload factor	100~160	%	150
<b>Par. Group02: Brake Function</b>				
C02.06	PM parking current	0~150	%	80
C02.07	PM parking time	0.1~60.0	s	3.0
<b>Par. Group03: Reference/Ramps</b>				
C03.03	Maximum Reference	0.0~6553.5	-	50.0
C03.10	Preset Reference	-100.00~100.00	%	0.00
C03.11	Jog speed	0.0~400.0	Hz	5.0
C03.15	Reference Source 1	0: No function 1: Terminal VI 2: Terminal AI	-	0
C03.16	Reference Source 2	8: Pulse input DI4 10: Preset reference [0]	-	2
C03.17	Reference Source 3	11: Local bus 21: LCP potentiometer	-	0
C03.41	Ramp 1 Ramp Up Time	0.05~655.35	s	*
C03.42	Ramp 1 Ramp Down Time	0.05~655.35	s	*
C03.51	Ramp 2 Ramp Up Time	0.05~655.35	s	*
C03.52	Ramp 2 Ramp Down Time	0.05~655.35	s	*
<b>Par. Group04: Limits/Warnings</b>				
C04.12	Motor Speed Low Limit	0.0~400.0	Hz	*
C04.14	Motor Speed High Limit	0.0~400.0	Hz	65.0
C04.16	Torque Limit Motor Mode	0~1000	%	*
C04.17	Torque Limit Generator Mode	0~1000	%	*
C04.18	Current Limit	0~300	%	200
C04.19	Max Output Frequency	0.0~400.0	Hz	65.0
C04.23	Power Limit Motor Mode	0~400	%	400
C04.24	Power Limit Generator Mode	0~400	%	400
C04.28	Low Voltage Overload Limit	5~100	%	100
C04.29	Low Voltage Udc Limit	50~1000	V	220/380
C04.61	Bypass Speed From	0.0~400.0	Hz	0.0
C04.63	Bypass Speed to	0.0~400.0	Hz	0.0
<b>Par. Group05: Digital In/Out</b>				
C05.04	DI Filter Time	0~32	ms	16
C05.05	DI Terminal Logic Selection	0~255	-	4
C05.10	Terminal FOR	0: No operation 1: Reset 2: Coast inverse 34: Ramp bit0 35: Ramp bit1	-	8
C05.11	Terminal REV	43: External alarm input 110: PID pause; 160: Compressor run; 161: Oil filter plugging; 162: Oil separator plugging 163: Air filter plugging; 164: Loading valve control; 165: Fan overload; 166: Motor over temperature; 167: Emergency stop; 168: External fault	-	0
C05.12	Terminal DI1	169: Phase sequence error 170: External sleep signal 171: Oil pump run detection 172: Cooling Fan Control	-	0
C05.13	Terminal DI2	173: Pulse Stop	-	0
C05.14	Terminal DI3	174: Pulse Start	-	0
C05.15	Terminal DI4		-	0

Par. No.	Name	Range	Unit	Default
C08.33	Parity/Stop Bits	0: No operation 1: Drive ready 5: Drive running 9: Alarm 10: Alarm or warning 38: Control by Communication 39: Control by DI Terminal 160: Loading valve; 161: Cooling fan; 162: Fan overload; 163: Pressure sensor error; 164: Temperature sensor error; 165: External error 1; 166: External dormancy function open; 167: External error 2; 168: Drain valve; 171: Oil pump control; 172: Error or maintain timeout 173: Dryer Control	-	2
C05.40	Relay Function		-	0
C14.01	Switching Frequency	2~6:2kHz~6kHz; 7:8kHz; 8:10kHz; 9:12kHz; 10:16kHz;	-	*
C14.10	Action at Mains Failure	0: No function 1: Ctrl ramp-down 2: Ctrl ramp-down, trip 3: Coasting 4: Kinetic back-up 5: Kinetic back-up, trip 6: Alarm 8: Warning	-	8
C14.11	Mains Voltage at Mains Failure	100~Rated Voltage	V	*
C14.12	Function at Mains Imbalance	0:Trip (Low sensitivity) 1:Warning (Low sensitivity) 2:Disabled 4:Warning (Middle sensitivity) 5:Trip (Middle sensitivity) 6:Trip (High sensitivity)	-	0
C14.14	Kinetic Backup Gain	0~500	%	100
C06.16	Terminal VI Filter Time	0.001~10.000	s	0.010
C06.22	Terminal AI Low Current	0.00~19.99	mA	4.00
C06.23	Terminal AI High Current	0.01~20.00	mA	20.00
C06.24	Terminal AI Low Ref/Feedb.Value	-200.00~200.00	%	0.00
C06.25	Terminal AI High Ref/Feedb.Value	-200.00~200.00	%	100.00
C06.26	Terminal AI Filter Time	0.001~10.000	s	0.010
<b>Par. Group07: Controllers</b>				
C07.20	Process PID Feedback Source	0: No function 1: Reference 2: Output Voltage 3: Output Torque 4: IGBT Temperature 5: DI Status 6: DO Status 7: Relay Status 8: VI Value	-	0
C07.30	Process PID Normal/Inverse	0: Normal 1: Inverse	-	0
C07.33	Process PID Proportional Gain	0.00~10.00	-	10.00
C07.34	Process PID Integral Time	0.01~655.35	s	12.00
C07.35	Process PID Differentiation Time	0.00~10.00	s	0.00
C07.36	Process PID Diff Gain Time	1.0~50.0	-	5.0
C07.38	Process PID Feed Forward Factor	0~400	%	0
C07.39	On Reference Bandwidth	0.0~200.0	%	0.0
C07.48	PID Max. Ref Coefficient	0.00~100.00	%	100.00
<b>Par. Group08: Communication</b>				
C08.01	Control Site	0: Digital and communication 1: Digital only 2: Communication only	-	0
C08.03	Communication Timeout Function	0: Off 1: Freeze output 2: Stop 3: Jogging 4: Max. speed 5: Stop and trip 6: Warning	s	10.00
C08.04	Reset Communication Timeout	0: Do not reset 1: Do reset 2: Stop and warning	-	2
C08.30	Protocol	0: FC; 2: MODBUS RTU;	-	2
C08.31	Address	1~247;	-	1
C08.32	Baud Rate	2: 9600; 3: 19200;	-	2

Par. No.	Name	Range	Unit	Default
C16.14	Output Current	0.00~655.35	A	0.00
C16.30	DC Link Voltage	0~65535	V	0
C16.34	IGBT Temperature	-128~127	°C	0
C16.48	Power Board Temperature	-128~127	°C	0
C16.49	Rectifier Temperature	-128~127	°C	0
C16.57	RI1 Temperature	-60~260	°C	0
C16.58	RI2 Temperature	-60~260	°C	0
C16.59	RI3 Temperature	-60~260	°C	0
C16.60	Digital Input	0~65535	-	0
C16.62	Analog Input VI	0.00~20.00	V/mA	0.00
C16.64	Analog Input AI	0.00~20.00	V/mA	0.00
C16.65	Analog Output VO	0.00~20.00	V/mA	0.00
C16.66	Digital Output	0~255	-	0
C16.71	Relay Output	0~65535	-	0
C16.78	Analog Output AO	0.00~20.00	V/mA	0
<b>Par. Group19: Cooling Fan</b>				
C19.00	Cooling Fan structure	0: ASYNCHRON 1: SPMSM 2: IPMSM_NON_SAT 3: IPMSM_SAT	-	0
C19.02	Cooling Fan Rated Power	Motor dependant	kW	*
C19.03	Cooling Fan Rated Frequency	0.0~400.0	Hz	50
C19.04[0]	Cooling Fan Rated Current	Motor dependant	A	*
C19.04[1]	Motor Fan Rated Current	Motor dependant	A	*
C19.05	Cooling Fan Rated Speed	0~9999	rpm	*
C19.06	Cooling Fan Speed Lower Limit	0.0~400.0	Hz	0.0
C19.07	Cooling Fan Speed Upper Limit	0.0~400.0	Hz	50.0
C19.08	Cooling Fan Max Frequency	0.0~400.0	Hz	50.0
C19.09	Cooling Fan Jog Frequency	0.0~50.0	Hz	5.0
C19.10	Cooling Fan Max Reference	0.0~6553.5	Hz	50.0
C19.11	Cooling Fan Ramp Up Time	0.05~3600.00	s	*
C19.12	Cooling Fan Ramp Down Time	0.05~3600.00	s	*
C19.15	Cooling Fan VF-U	*	V	*
C19.16	Cooling Fan VF-F	*	Hz	*
C19.17	Min Speed for Function at Stop	0.0~400.0	Hz	*
C19.18	Cooling Fan Rated Torque	0.1~6553.5	NM	*
C19.19	Cooling Fan Motor Poles	2~100	P	4
C19.20	Cooling Fan EMF in 1000 rpm	0~9000	V	*
C19.21	Cooling Fan AMA	0: No function 1: Static complete AMA	-	0
C19.22	Cooling Fan Stator Resistance	Motor dependant	Ω	*
C19.23	Cooling Fan Rotor Resistance	Motor dependant	Ω	*
C19.24	Cooling Fan Stator Leakage Reactance	Motor dependant	Ω	*
C19.25	Cooling Fan Main Reactance	Motor dependant	Ω	*
C19.26	Cooling Fan D-axis Inductance	Motor dependant	mH	0
C19.27	Cooling Fan Q-axis Inductance	Motor dependant	mH	0
C19.28	D-axis Inductance Sat.	Motor dependant	Ω	*
C19.29	Q-axis Inductance Sat.	Motor dependant	Ω	*
C19.30	Current at Min Inductance for D-axis	20~200	%	100
C19.31	Protocol	0: FC; 2: MODBUS RTU;	-	2
C19.32	Address	1~247;	-	1
C19.33	Baud Rate	2: 9600; 3: 19200;	-	2
<b>Par. Group16: Data Readouts</b>				
C16.00	Control Word	0~65535	-	0
C16.01	Internal Fault Reason	-32767~32767	-	0
C16.32	Frequency at Alarm	0.0~6553.5	Hz	0.0
C16.33	Current at Alarm	0~65535	A	0.00
C16.34	DC Voltage at Alarm	0~65535	V	0
C16.35	Runtime at Alarm	0.0~6553.5	min	0.0
C16.36	Custom defined value 1 at Alarm	0~65535	-	0
C16.37	Custom defined value 2 at Alarm			